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Today a general, there is an increasing and widespread need for robots assisting different to assist with a range of human activities goes up. The goal of the present project study is to develope a general-purpose frame-work framework, which provides for attaching and fitting different kindstypes of sensors and actuators. These general purpose This framework gives provides an easy way tooto turn general-purpose robots with ainto special-function one ones. The final concreteultimate goal of the present study developement is to developing the develop an autonomous robotic to assisting clinicallyclinical patients and the or elderly person's. The attached sensors collectingcollect information using from the surrounding worlds robot's surroundings and send it to an FPGA board. The FPGA broad will, which controls the sensor's sensors and processed processes the measured values. With Using the measured data, the FPGA board can controls the -robot's movement. The chosen implementation platform chosen-was a Nexys 3 Spartan-6 FPGA Board board. The sensors (light Light, humidity, and temperature) attaching sensors <u>are attached</u> to the board, and the <u>processprocessed</u> values <u>comeare shown</u> on <u>graphicsa graphical</u> display. Finally, the robots can communicating to communicate with each other with the <u>Digilent</u> PmodRF2-IEEE 802.15 RF-Transceiver, transceiver. Fig. 1 showedshows the schemedesign of the robot.

The project consisting in comprises two majormain components—the robot, and a cell phone.

Between a, The robot and the cell phone communications communicate is gotten using Bluetooth module's. The software is implemented was done through in the Verilog hard—ware hardware description language and java (android the Java (Android SDK) program) programming language. The PmodOLED's controller code were for controlling the Digilent Pmod OLED screen is written on in the C programming language and runs in the on a PIC18F45K20 micro—controller.

Robot The robot is equipped with a Nexys3 Nexys 3 FPGA Board with XILINX SPARTAN-board based on a Xilinx Spartan-6 FPGA, which controls a the attached peripheral devices. It has a two analog

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Comment [A1]: Prepositional phrases should be set off from the main clause using a comma.

Comment [A2]: Some adjectives stand for a group or people who share the same characteristic so they function as nouns. In such cases, "the" is placed before such words and a plural verb is used.

Comment [A3]: If the first letter of a word has a vowel sound, you use "an"; if the first letter has a consonant sound, you use "a." Pronounce the word and select the correct article.

Comment [A4]: To use the colon correctly, you must make sure that sentence that comes before the colon is a complete, grammatical sentence.

Comment [A5]: In American English, that is used to introduce a restrictive clause and which a nonrestrictive clause.

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Sensor:sensors: a light "sensor" (photo-resistor) and a humidity sensor (Samyoung SYH-2R).

PmodAD1 converted). A Digilent Pmod AD1 converts the analog signal's signals into digital value's and thanvalues for processing by the FPGA can process the measured values. A DS18S20 digital thermometer is used for measuring the temperature—Lit has a which is accurate to within 0.5C accuracy5°C between 1-10°C to and +85°C. The FPGA broadboard collects the measured values and; then evaluates these. Using a them. The robot uses a Nuvoton ISD1760 voice recording and playback device the robot oplay back template voices template accordingly to the based on measureing measured values. A PIC18F45K20 micro-controller microcontroller communicates with the FPGA board and handle PmodOLED handles the display, which displaying evaluated shows the measured humidity; and light level information. What is more it include an It also includes a Rayson BTM; 222 Bluetooth module—It can communicates using, enabling it to communicate with a cell phone (running the Android operating system). Based on the phone their is a android operation system) and according on a received information received from the cell phone, it instructs the FPGA will be handles the movements of to activate the motors accordingly.

Comment [A6]: A minus sign (-) instead of a hyphen (-) can should be used to indicate negative values.